

File List

Here is a list of all documented files with brief descriptions:

[detail level 1 2 3 4 5]	
▼ client	
▼ C++	
▼ example	
▼ include	
airbot_example.hpp	Example usage of the AirbotSdk class
▼ include	
airbot_sdk.hpp	Main SDK interface for controlling Airbot robotic arm
driver_state.hpp	Defines operational states for the driver service
robot_mode.hpp	Defines control modes for robot arm operations
speed_profile.hpp	Defines speed profiles for robot motion control